

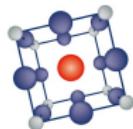
Depinning transition for domain walls with an internal degree of freedom

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Thierry Giamarchi¹

¹Département de Physique de la Matière Condensée, Genève

²Physics Department, University of Miami

³Département de Physique Théorique et Section de Mathématiques, Genève



MaNEP
SWITZERLAND

Genève – 13th March 2009



**UNIVERSITÉ
DE GENÈVE**

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Outline

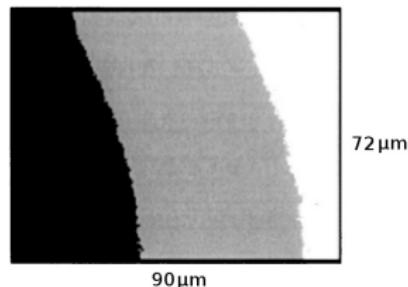
① Interface Physics

- Systems
- Depinning transition
- Experiments

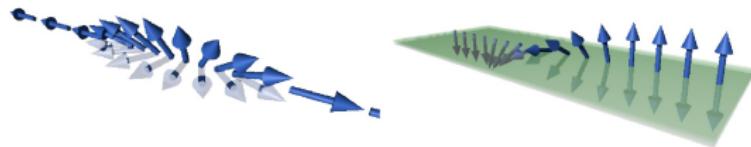
② Depinning with internal degree of freedom

- Modelisation
- Dynamics

Magnetic domain wall

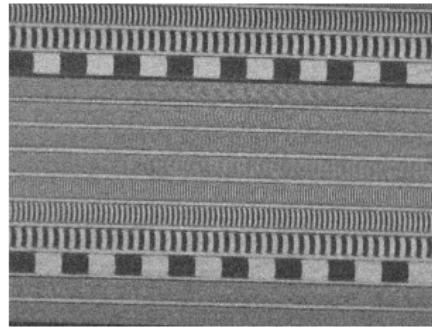


from Lemerle *et al.*, PRL **80** 849 (1998)

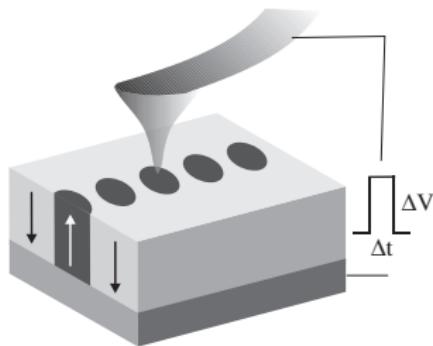
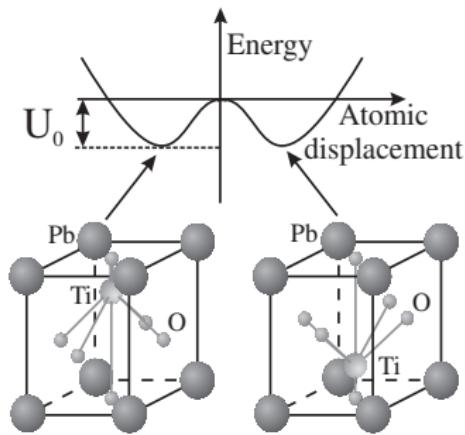


from Tatara *et al.*, J. Phys. Soc. Jap **77** 031003 (2008)

Magnetic domains

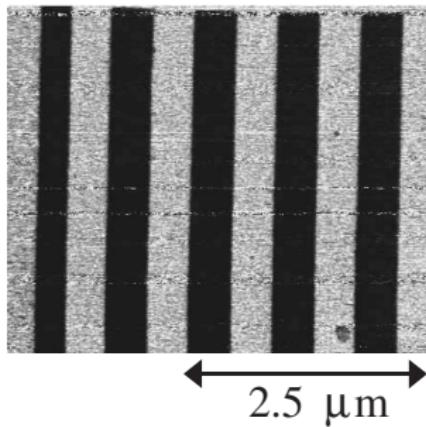
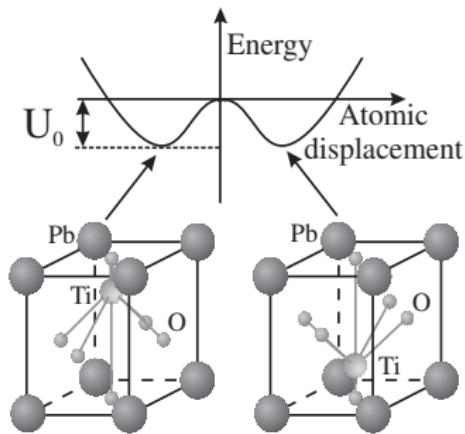


Ferroelectric domain wall



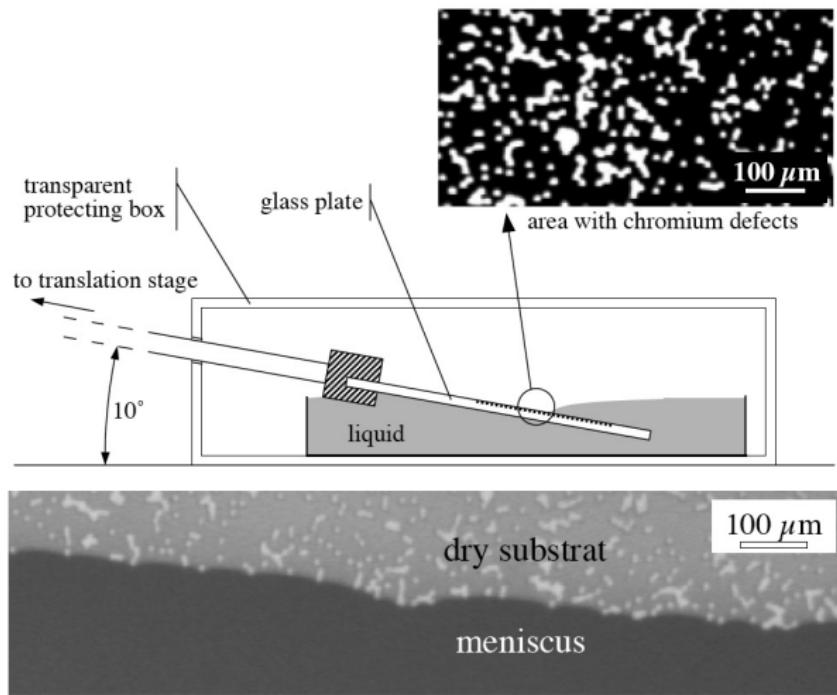
from Paruch et al. *J. Appl. Phys.*, **100** 051608 (2006)

Ferroelectric domain wall



from Paruch *et al.* *J. Appl. Phys.*, **100** 051608 (2006)

Contact line of a fluid



from Moulinet, Guthmann and Rolley, *Eur. Phys. J. E*, **8** 437 (2002)

Common underlying description?

Large range of physical scales

- magnetic/ferroelectric domain walls
- growth interfaces
- contact line
- crack propagation

Questions

- Statics
 - fluctuations, roughness
- Non-equilibrium **dynamics**
 - motion of the interface
- Nature, role of **disorder**

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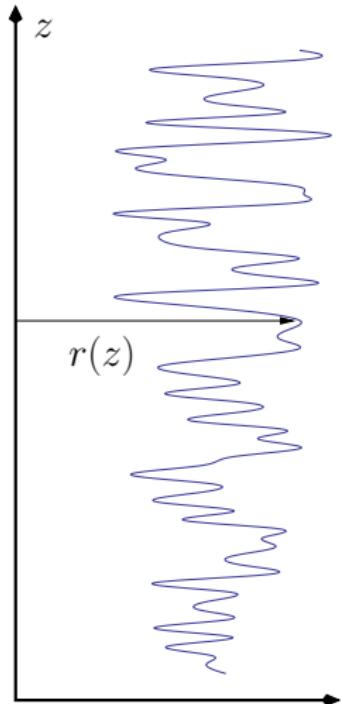
Disordered elastic systems

- Elasticity: tends to flatten the interface

$$\frac{c}{2} \int dz (\nabla r(z))^2$$

- Disorder: tends to bend it

$$\int dz V(r(z), z)$$



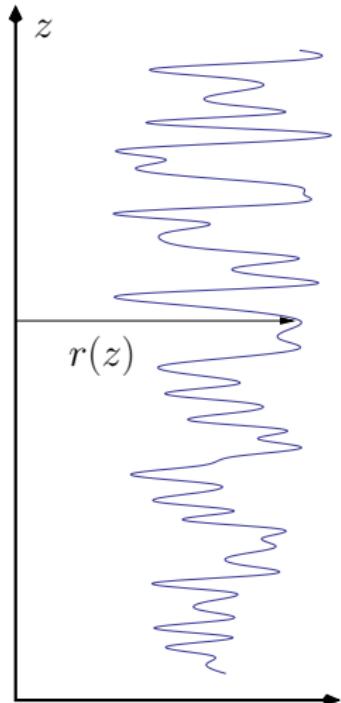
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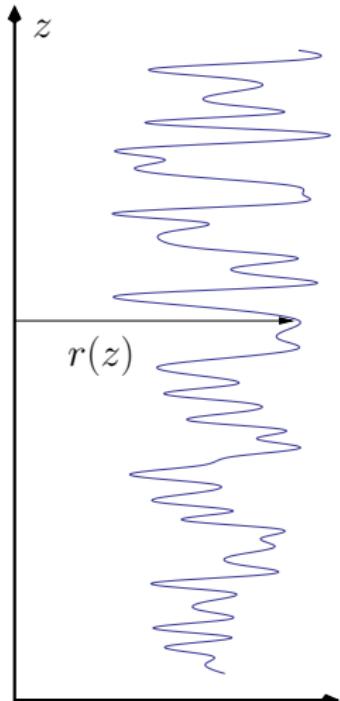
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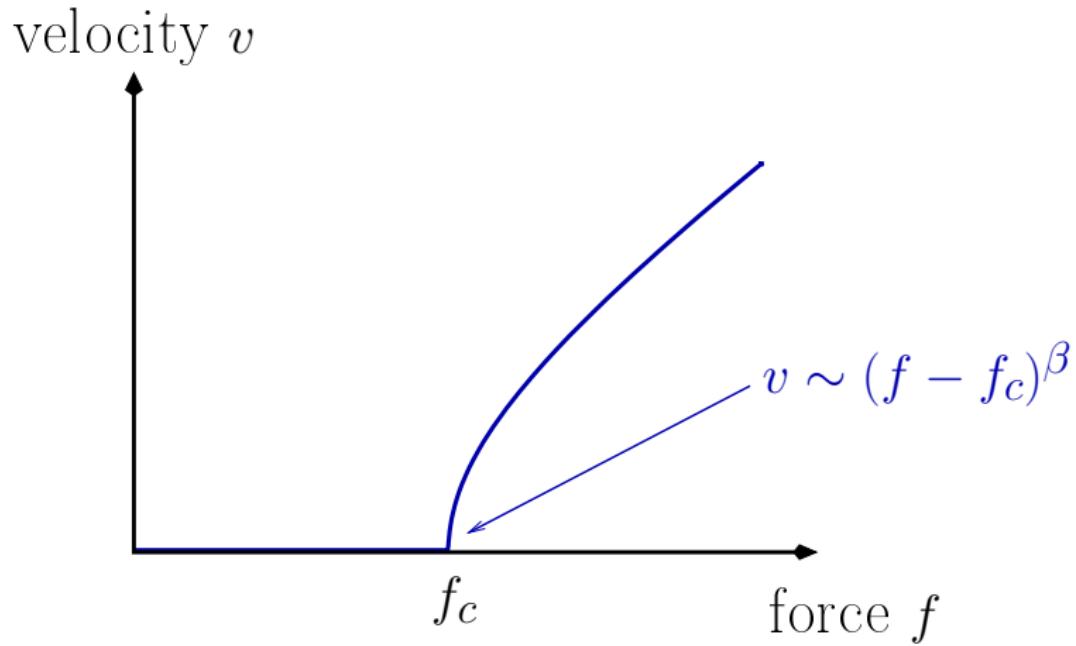
Competition btw “order” and “disorder”

Is $r(z)$ containing enough?

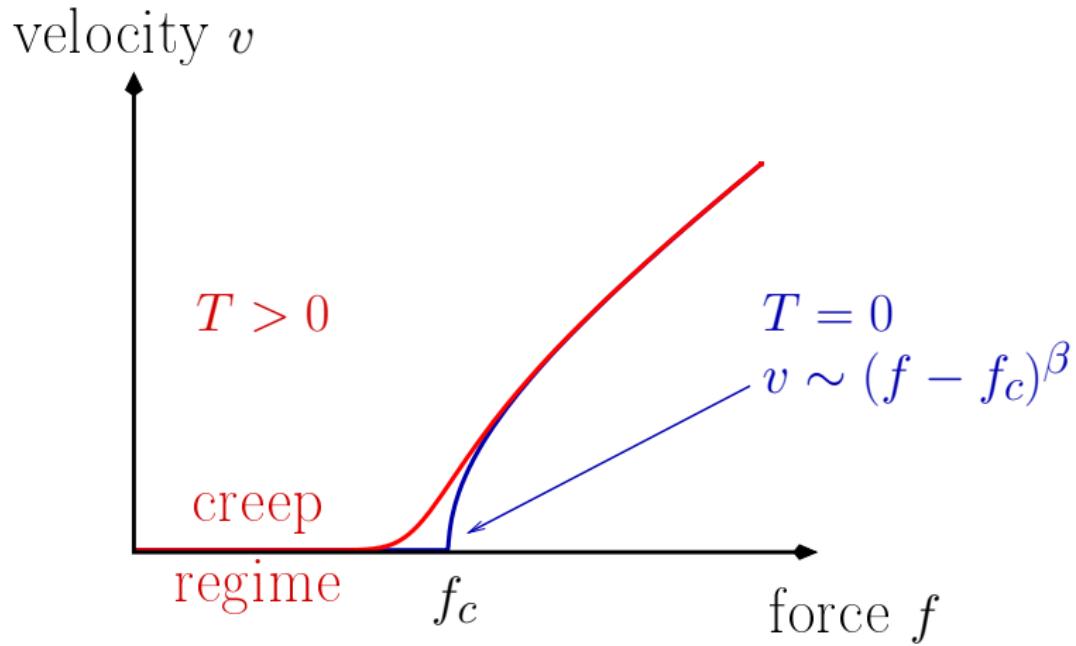
Is $r(z)$ containing enough?

→ Have a look to the dynamics in simple examples.

Depinning transition @ zero temperature

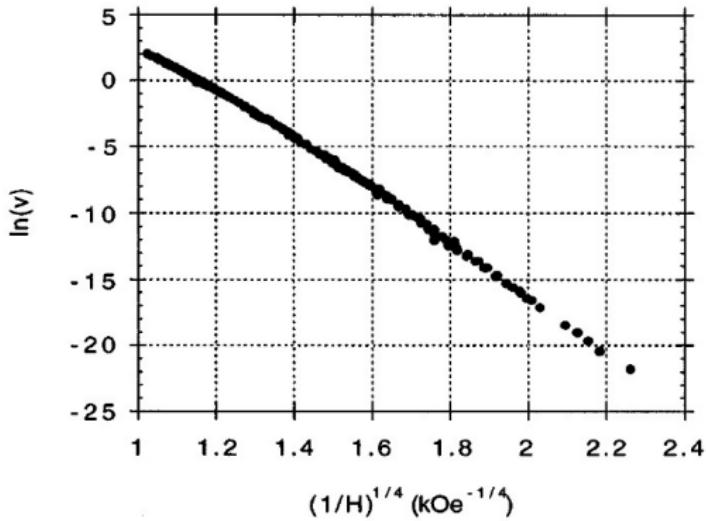


Depinning transition @ finite temperature



Comparison with experiment: ferromagnetic films

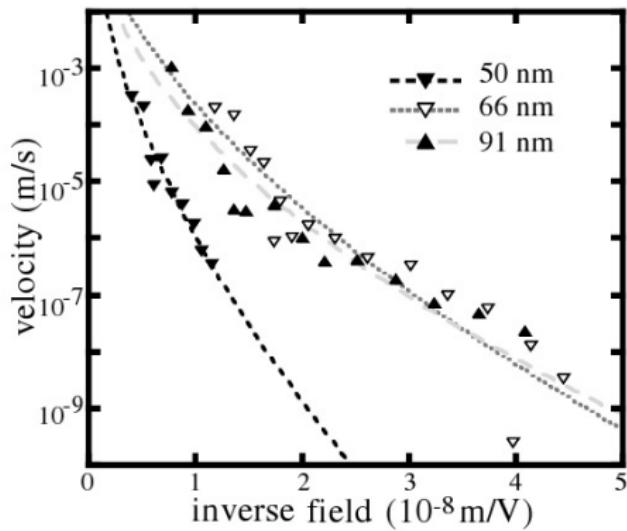
$$\nu(f) \sim \exp \left[-\frac{U_c}{T} \left(\frac{f_c}{f} \right)^\mu \right] \quad (\text{creep})$$



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Comparison with experiment: ferroelectric films

$$v(f) \sim \exp \left[-\frac{U_c}{T} \left(\frac{f_c}{f} \right)^\mu \right] \quad (\text{creep})$$



from Paruch *et al.*, PRL 94 197601 (2005)

Comparison with experiment

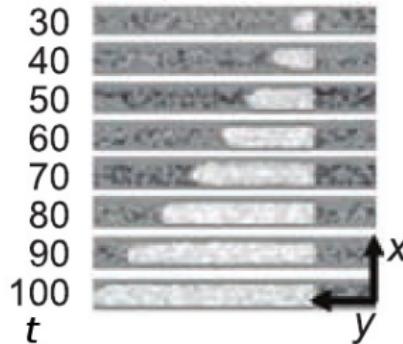
BUT...

Comparison with experiment: ferromagnetic wire

$$v(f) \sim \exp \left[-\frac{U_c}{T} \left(\frac{f_c}{f} \right)^\mu \right] \quad (\text{creep})$$

	Field drive		Current drive	
	μ^*	σ^*	μ	σ
Experiment	1.2 ± 0.1	1.4 ± 0.1	0.33 ± 0.06	2.0 ± 0.2
Theory	1.0	1.5	0.5	1.25

from Yamanouchi *et al.*, Science 317 1726 (2007)

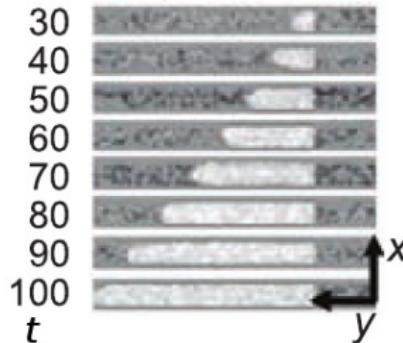


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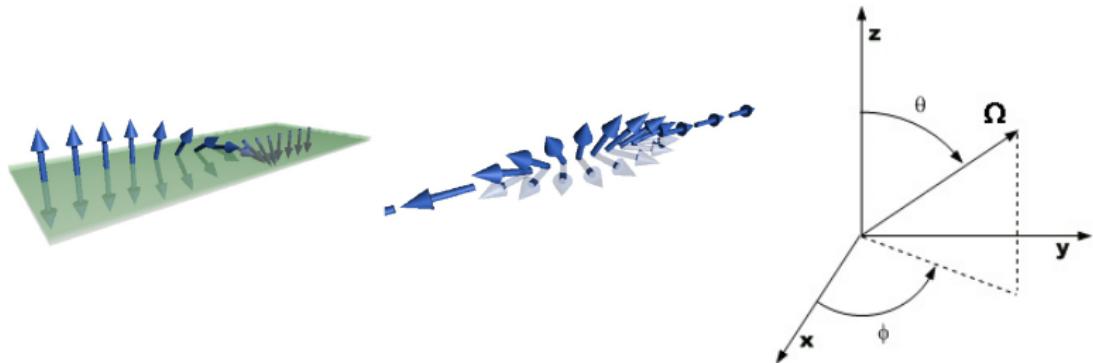
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② Depinning with internal degree of freedom

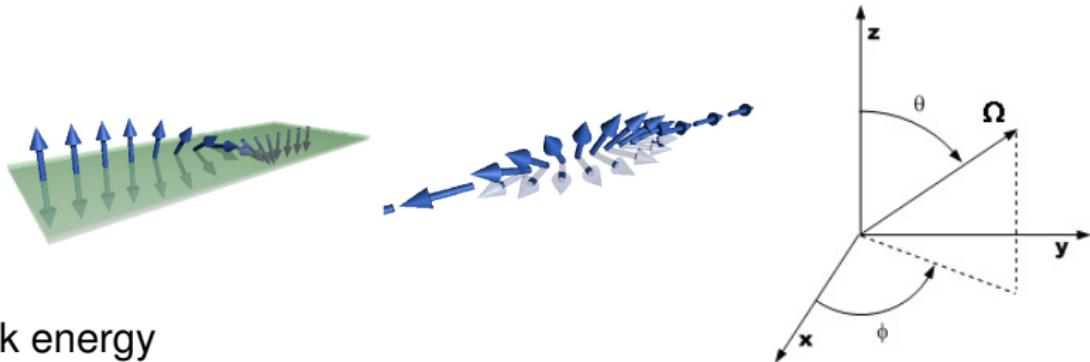
- Modelisation
- Dynamics



Bulk model



Bulk model



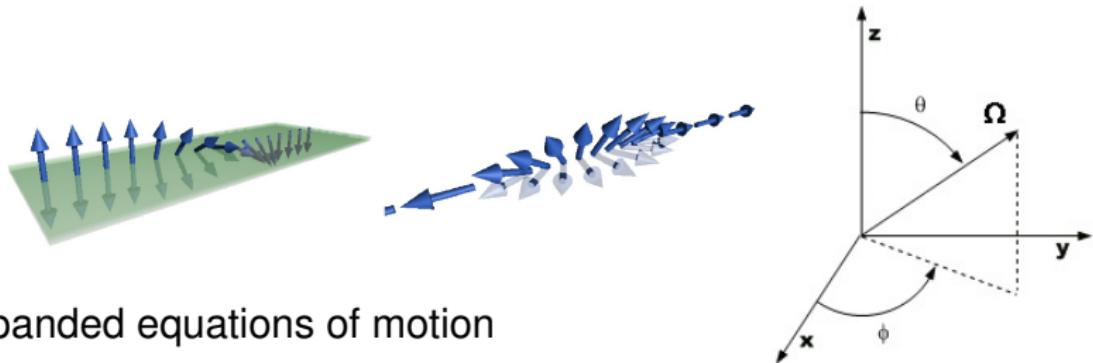
- Bulk energy

$$E = \int d^d x \left\{ J [(\nabla \theta)^2 + \sin^2 \theta (\nabla \phi)^2] + K \sin^2 \theta + K_{\perp} \sin^2 \theta \cos^2 \phi \right\}$$

- Equation of motion

$$(\partial_t + \mathbf{v}_s \cdot \nabla) \Omega = \Omega \times \left(\frac{\delta E}{\delta \Omega} + \mathbf{f} + \boldsymbol{\eta} \right) - \Omega \times (\alpha \partial_t + \beta \mathbf{v}_s \cdot \nabla) \Omega$$

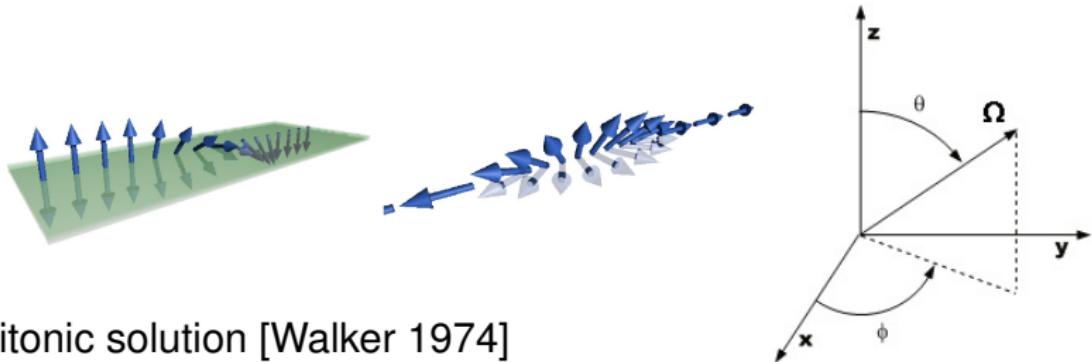
Bulk model



- Expanded equations of motion

$$\begin{aligned}\partial_t \theta - \alpha \sin \theta \partial_t \phi + v_s (\partial_x \theta - \beta \sin \theta \partial_x \phi) &= -\frac{1}{2} K_\perp \sin \theta \sin 2\phi - \frac{J}{\sin \theta} \partial_x (\sin^2 \theta \partial_x \phi) \\ \sin \theta \partial_t \phi + \alpha \partial_t \theta + v_s (\sin \theta \partial_x \phi + \beta \partial_x \theta) &= -\frac{1}{2} K_\perp \sin 2\theta \cos^2 \phi - \frac{1}{2} (K + J(\partial_x \phi)^2) \sin 2\theta \\ &\quad - H_{\text{ext}} \sin \theta + J \partial_x^2 \theta\end{aligned}$$

Bulk model



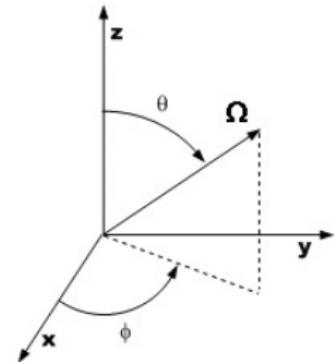
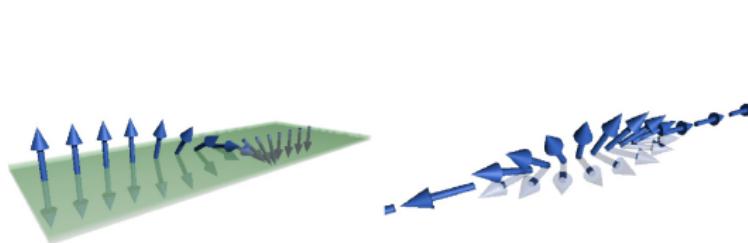
- Solitonic solution [Walker 1974]

$$\sin 2\phi(x, t) = \frac{f}{f_W} \quad f_W = \frac{1}{2}\alpha K_{\perp}$$

$$\theta(x, t) = 2 \arctan \exp \left\{ \left[1 + \frac{K_{\perp}}{K} \cos^2 \phi \right]^{\frac{1}{2}} \left(\sqrt{\frac{K}{J}} x - vt \right) \right\}$$

$$v = \frac{H_{\text{ext}}}{H_c} \left[1 + \frac{K_{\perp}}{K} \cos^2 \phi \right]^{-\frac{1}{2}}$$

Bulk model



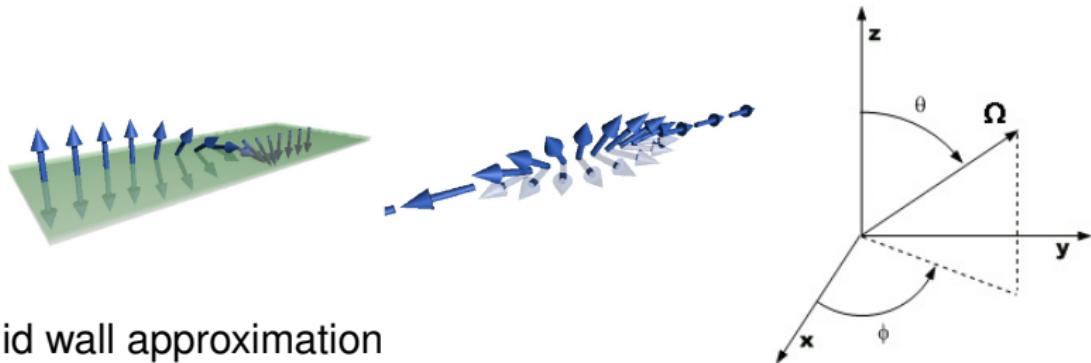
- Rigid wall approximation

$$\alpha \partial_t \mathbf{r} - \partial_t \phi = \mathbf{f} + \text{Landscape} \quad + \eta_1$$

$$\alpha \partial_t \phi + \partial_t \mathbf{r} = -\frac{1}{2} K_{\perp} \sin 2\phi \quad + \eta_2$$

Unit of length: $\sqrt{J/K}$

Bulk model



- Rigid wall approximation

$$\alpha \partial_t r - \partial_t \phi = f - \cos \kappa r + \eta_1$$

$$\alpha \partial_t \phi + \partial_t r = -\frac{1}{2} K_{\perp} \sin 2\phi + \eta_2$$

- Effective model:

Position $r(t)$ coupled to phase $\phi(t)$.

Depinning @

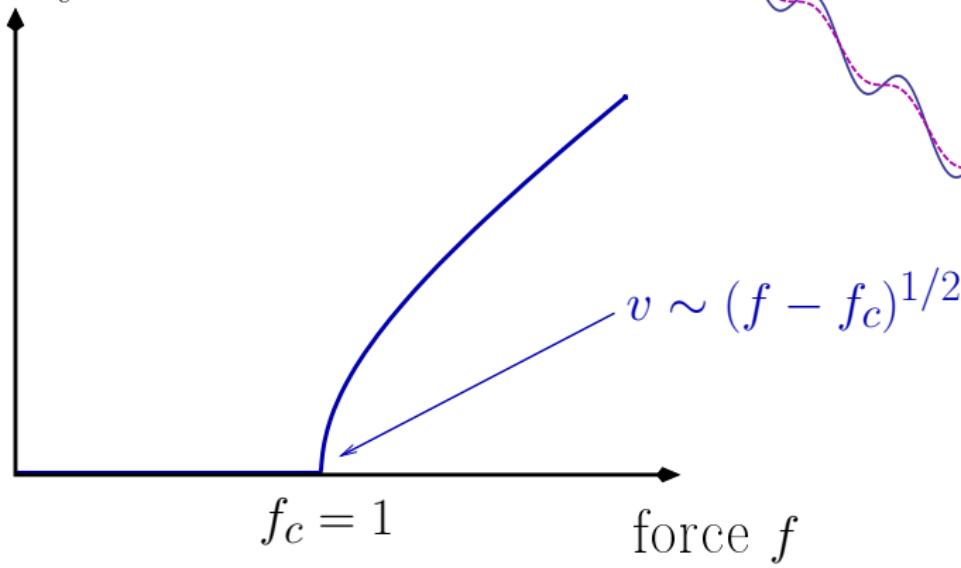
Large K_{\perp} : ϕ decouples from r

Depinning @ zero temperature

Large K_{\perp} : ϕ decouples from r

$$\alpha \partial_t r = f - \cos \kappa r$$

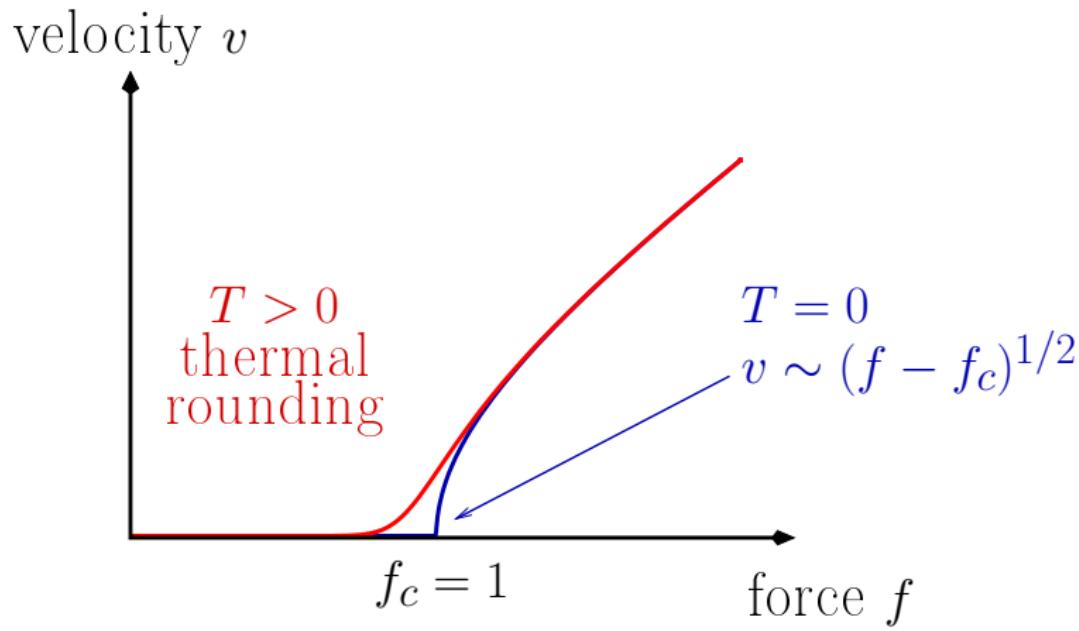
velocity v



Depinning @ finite temperature

Large K_{\perp} : ϕ decouples from r

$$\alpha \partial_t r = f - \cos \kappa r + \eta$$



Depinning @ zero temperature

Smaller K_{\perp} : ϕ matters

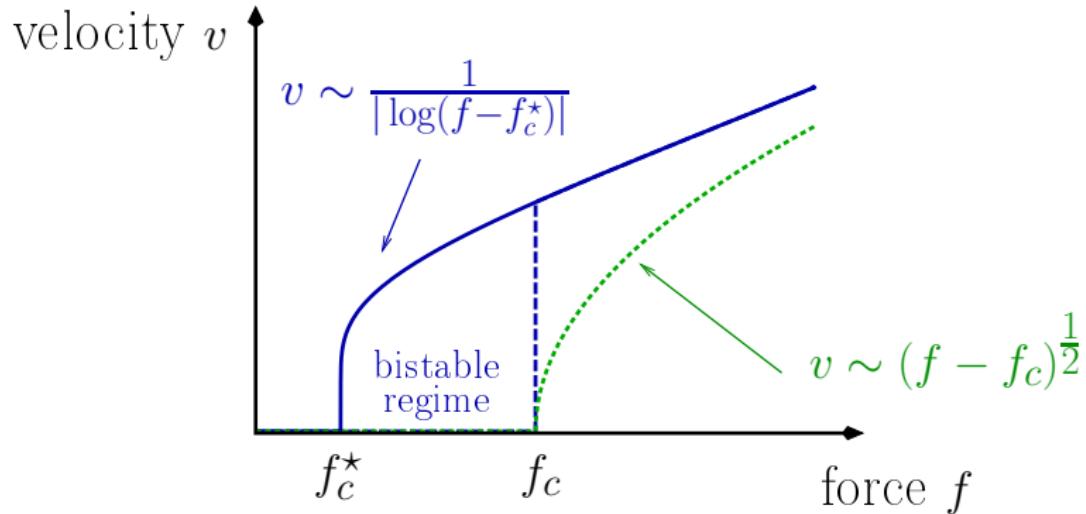
$$\alpha \partial_t r - \partial_t \phi = f - \cos \kappa r$$

$$\alpha \partial_t \phi + \partial_t r = -\frac{1}{2} K_{\perp} \sin 2\phi$$

Depinning @ zero temperature

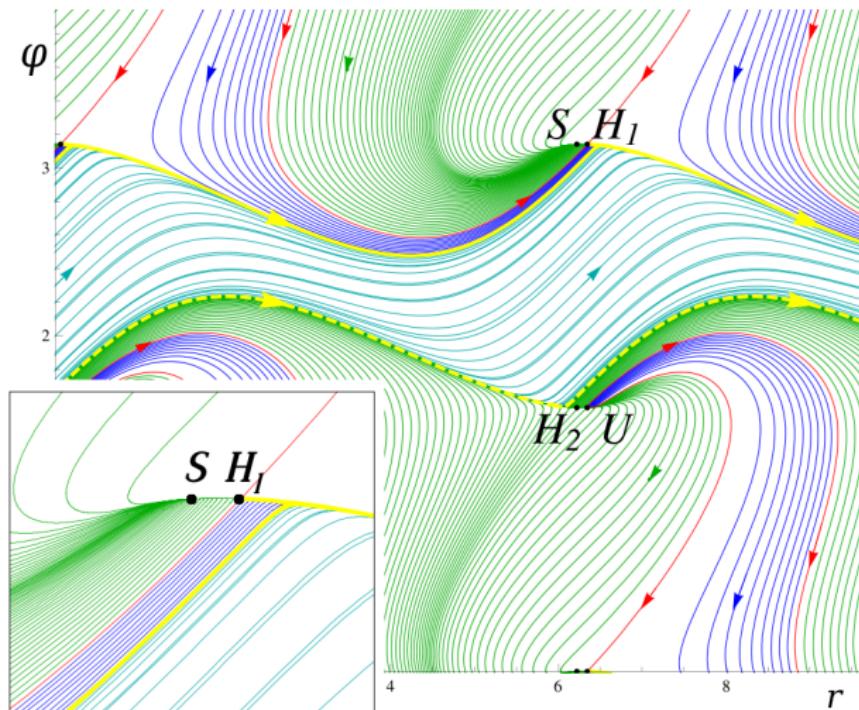
Smaller K_{\perp} : ϕ matters

- Dramatic change in the depinning law: $v \sim \frac{1}{|\log(f-f_c^*)|}$



- Depinning at **lower** critical force: $f_c^* < f_c$
- Bistability

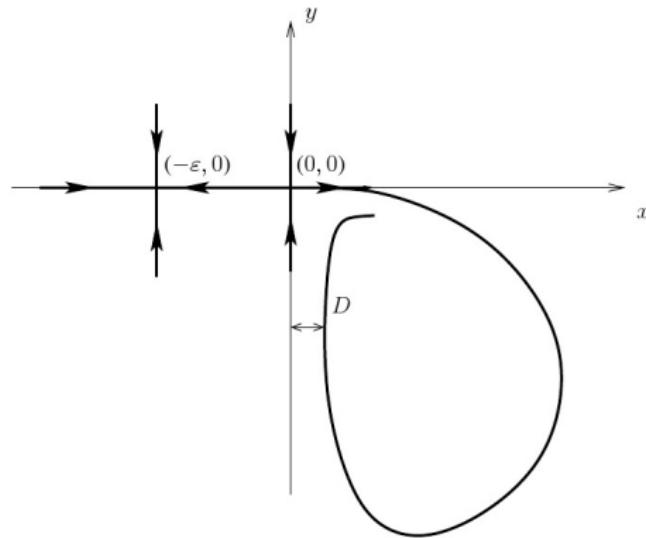
Phase space



In the bistable regime ($f_c^* < f < f_c$)

Phase space

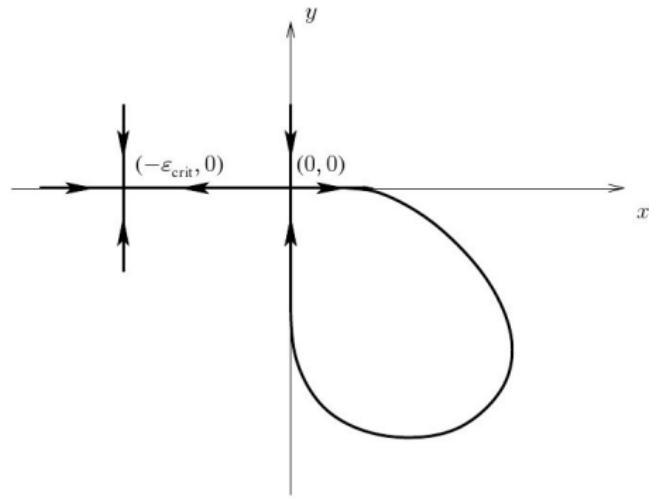
Homoclinic bifurcation:



$$f > f_c^*$$

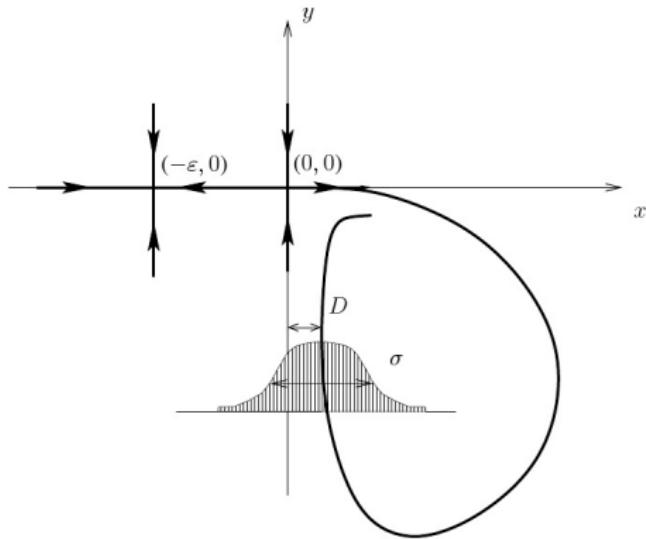
Phase space

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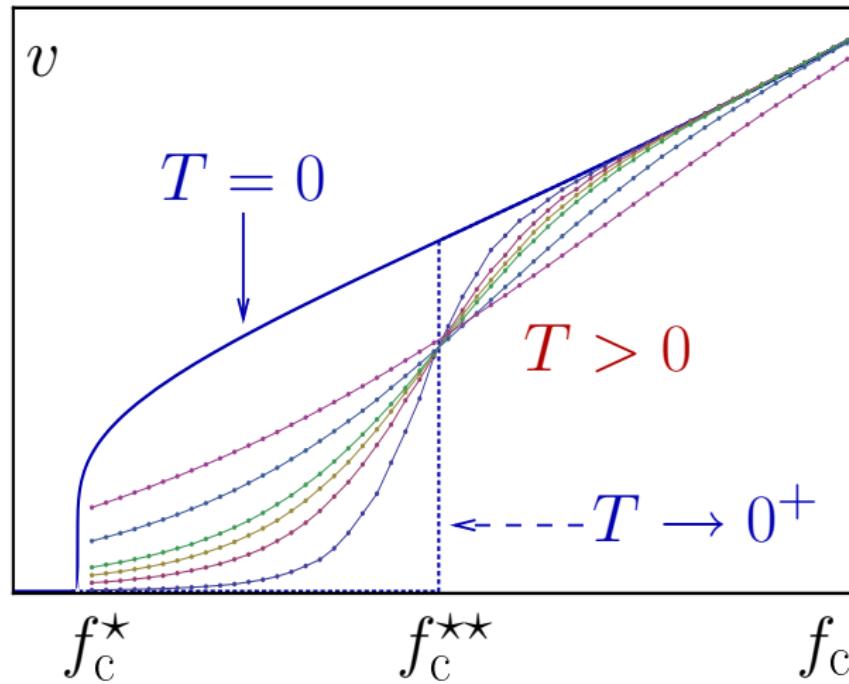
$$f = f_c^*$$

Finite temperature



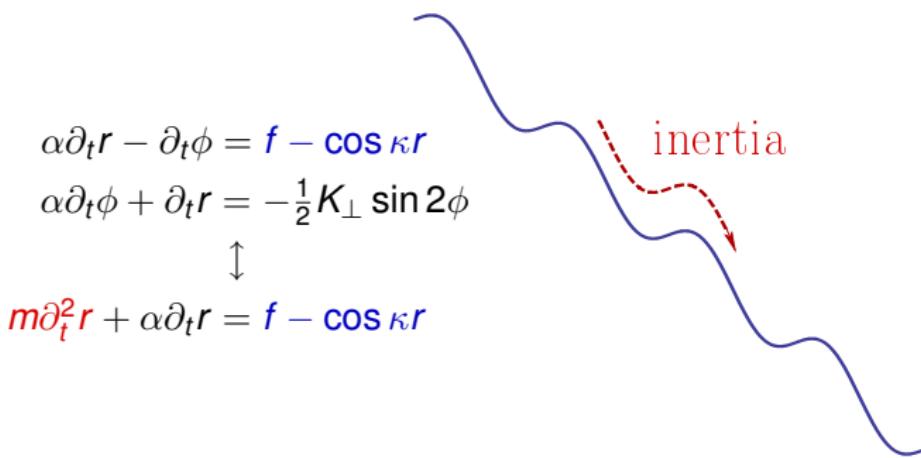
$$\text{escape time} \sim \underbrace{\exp\left(\frac{\epsilon^3}{T}\right)}_{\text{Arrhenius}} \underbrace{\exp\left(-\frac{A}{T}(\epsilon - \epsilon_c)^2\right)}_{\text{Trapping probability}}$$

Finite temperature



Force-velocity characteristics

Analogy

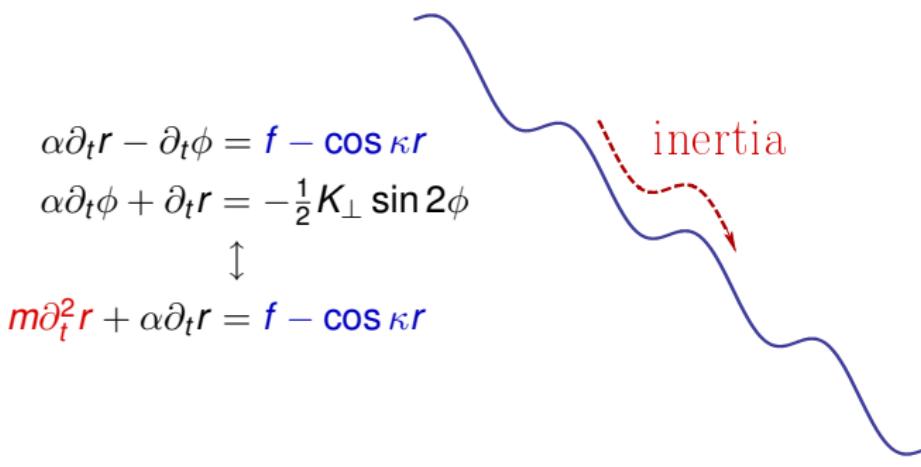


The phase ϕ plays the role of a velocity:

inertia helps to cross barriers

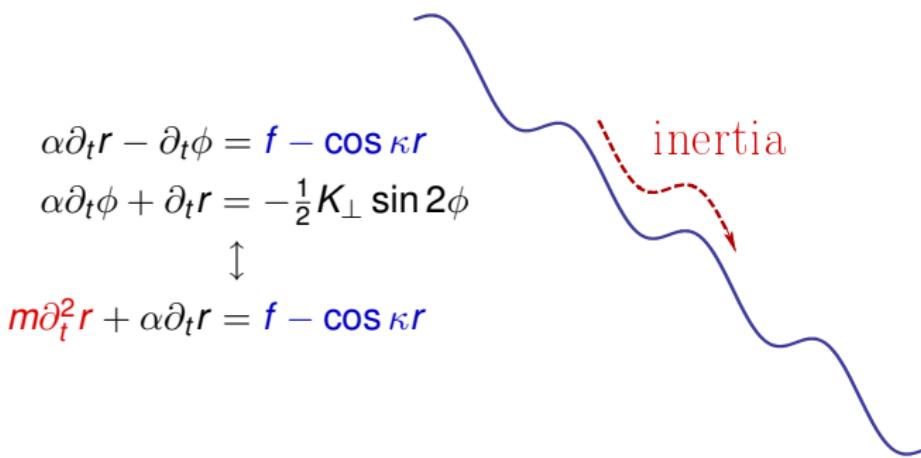
[see also Risken chap.11]

Analogy



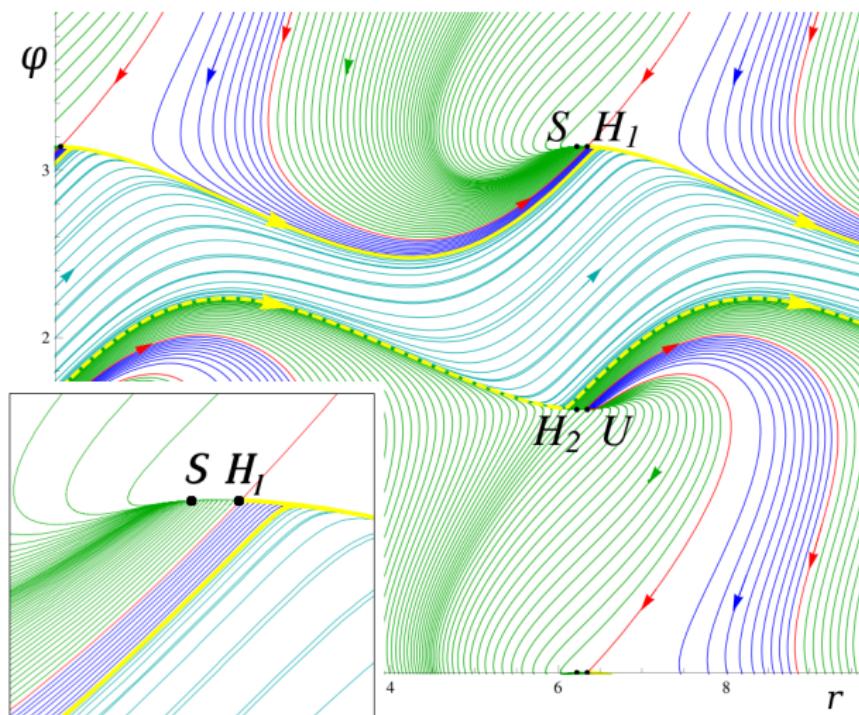
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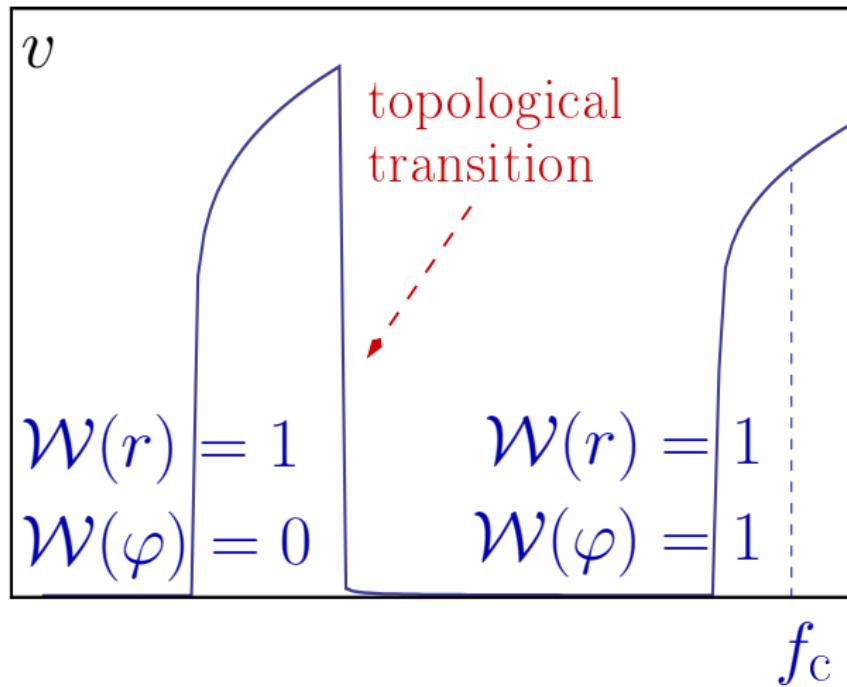


the velocity is **unbounded** **WHEREAS** ϕ is **bounded** and periodic

Topological transition

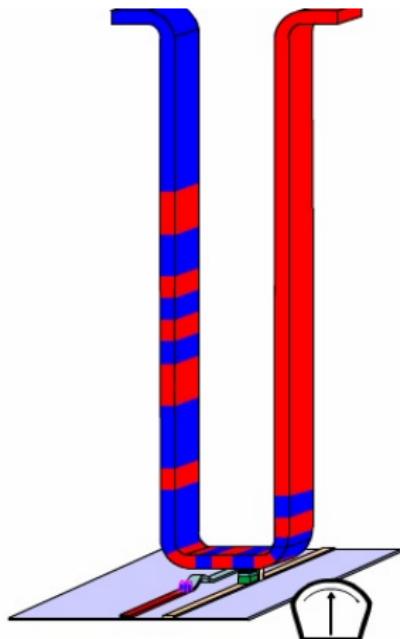


Topological transition

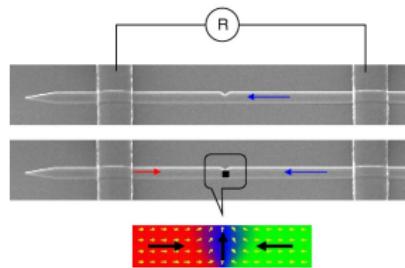


Successive regimes characterized by winding numbers \mathcal{W}

Experiment



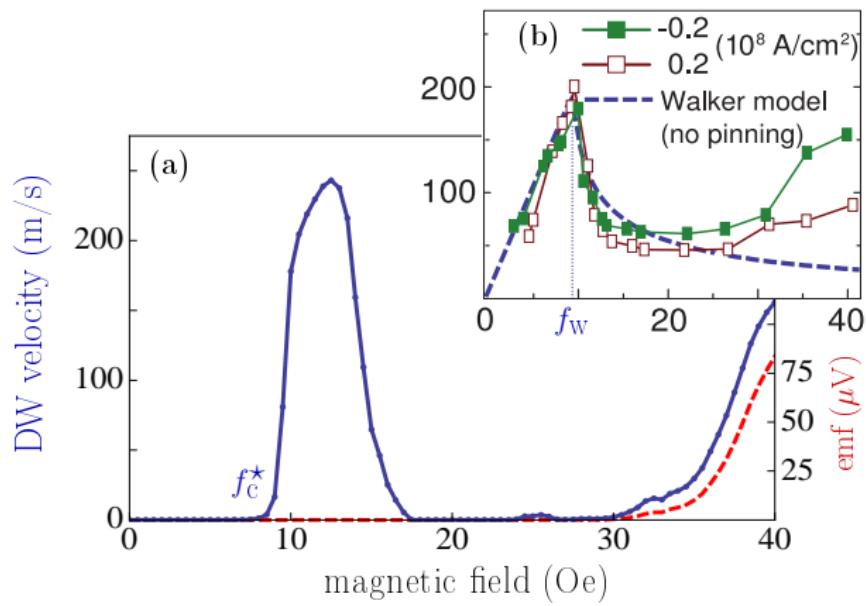
SPINTRONICS



from Parkin *et al.*, Science **320** 190 (2008)

Experiment

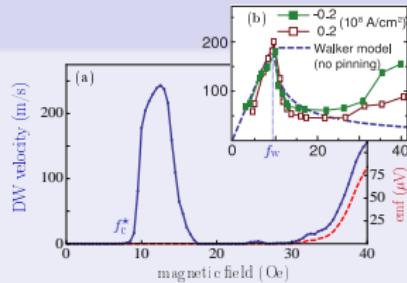
experiment from Parkin *et al.*, Science 320 190 (2008)



Outlook

Internal degree of freedom

- unusual depinning law
- bistability
- non-monotonous $v(f)$ at finite T
- link with experiments



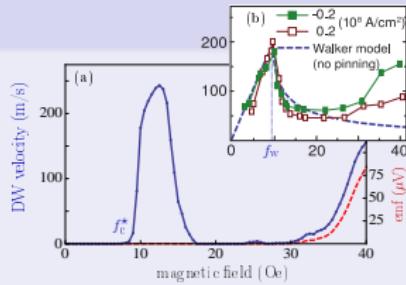
Perspective

- Current driven wall
- Interface with elasticity
→ modified creep law?
- Experiments
periodic patterning

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