Population dynamics and rare events

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Why studying rare events?



2003 heat wave, Europe [Terra MODIS]

Vivien Lecomte (LIPhy)

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[Anomaly for 1-month average] 2003 heat wave, Europe [Terra MODIS]

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Motivations

Why studying rare events?



2010 heat wave in Western Russia [Dole et al., 2011]

Motivations

Why studying rare events?



How to study rare events?

Questions for physicists and mathematicians:

- Probability and dynamics of rare events?
- How to sample these in numerical modelisation?
- Numerical tools and methods to understand their formation?

Outline

Introduction

• Tools and algorithm:

Large deviation functions Ingredient 1/2: population dynamics Ingredient 2/2: change of ensemble

Use, extensions and limitations of population dynamics: Different averages Feedback method Finite-time and finite-population scalings

• Open questions

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Open questions

Time-extensive observable on a time window $[0, t_f]$

Tools

• Climate dynamics:

$$\int_{0}^{t_{\rm f}} dt \, \, {\rm temperature}(t)$$

• Fluctuating thermodynamics:

work =
$$\int_0^{t_{\rm f}} dt \, \operatorname{force}(t) \cdot \operatorname{velocity}(t)$$

Road traffic:

#{cars passing through a gate}

• Molecular transport:

 $\#\{\text{steps of a motor on a filament}\}$

• Lattice gases in 1d:

"current" = #{jumps to the right} - {jumps to the left} "activity" = #{jumps to the right} + {jumps to the left}

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Tools



 $\begin{array}{l} \mathsf{Prob}[\mathcal{K},t] \sim \mathrm{e}^{t\,\varphi(\mathcal{K}/t)} \text{ as } t \to \infty \qquad \varphi(k) = \text{large deviation function} \\ \text{quadratic approx. } \varphi(k) = \frac{(k-\bar{k})^2}{2\sigma^2} + \dots \quad \leftrightarrow \quad \text{Gaussian fluctuations} \end{array}$

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Population dynamics & rare events

Aim: modify dynamics to make atypical values k typical

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Original dynamics: \overline{k} is typical and k atypical Construct a modified dynamics where k is now typical?

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Ingredient 1/2: population dynamics



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Many copies of the system of interest evolve in parallel.

Ingredient 1/2: population dynamics



Tools

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Ingredient 1/2: population dynamics



Many copies of the system of interest evolve in parallel. **Selection rules** favor the normally atypical value of k

 \rightarrow typical population trajectories sample trajectories at K/t = k

Consider an observable $\mathcal{O}[trajectory]$.

$$\underbrace{\frac{\left\langle \mathcal{O}[\mathsf{traj.}] \,\delta\left(\frac{1}{t}K[\mathsf{traj.}] - \mathbf{k}\right)\right\rangle}{\left\langle \delta\left(\frac{1}{t}K[\mathsf{traj.}] - \mathbf{k}\right)\right\rangle}}$$

average of \mathcal{O} for trajectories with atypical $\mathbf{k} = \mathbf{K}/t$

=

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average of \mathcal{O} for trajectories with atypical $\mathbf{k} = \mathbf{K}/t$



average of ${\mathcal O}$ for trajectories with a bias ${\rm e}^{-s\,{\mathcal K}}$

For *s* and *k* suitably "conjugated".

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Analogy: $k \equiv \text{energy/volume}$; $s \equiv \text{inverse temperature } \beta$

Correspondences:

Fixed $k = K/t \iff \text{bias by } e^{-sK}$

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Relation between *s* and *k*; Cumulant Generating Function (CGF):

$$\operatorname{Prob}\left[K/t=k\right] \sim e^{t\varphi(k)} \qquad \Longleftrightarrow \qquad \left\langle e^{-sK} \right\rangle \sim e^{t\frac{\zeta GF}{\psi(s)}}$$

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Saddle-point at large t:

$$\max_{\mathbf{k}} \left\{ \varphi(\mathbf{k}) - \mathbf{s} \, \mathbf{k} \right\} = \psi(\mathbf{s})$$

Maximum reached for k conjugated to s

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Remaining question: how to represent e^{-sK} by pop. dynamics?

(for jump processes)

• Markov processes: $\partial_t P(\mathcal{C}, t) = \sum_{\mathcal{C}'} \left\{ \underbrace{\mathcal{W}(\mathcal{C}' \to \mathcal{C}) P(\mathcal{C}', t)}_{\text{gain term}} - \underbrace{\mathcal{W}(\mathcal{C} \to \mathcal{C}') P(\mathcal{C}, t)}_{\text{loss term}} \right\}$

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Tools

• More detailed dynamics for P(C, K, t):

$$\partial_t P(\mathcal{C}, \mathbf{K}, t) = \sum_{\mathcal{C}'} \left\{ W(\mathcal{C}' \to \mathcal{C}) P(\mathcal{C}', \mathbf{K} - 1, t) - W(\mathcal{C} \to \mathcal{C}') P(\mathcal{C}, \mathbf{K}, t) \right\}$$

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$$\mathbf{K} = \mathbf{k}_{\mathcal{C}_0 \mathcal{C}_1} + \mathbf{k}_{\mathcal{C}_1 \mathcal{C}_2} + \dots$$

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Numerical method [JB Anderson; D Aldous; P Grassberger; P Del Moral; ...]

Evaluation of large deviation functions [à la "Diffusion Monte-Carlo"]

$$\sum_{\mathcal{C}} \hat{P}(\mathcal{C}, \boldsymbol{s}, t) = \left\langle e^{-\boldsymbol{s} \cdot \boldsymbol{K}} \right\rangle \sim e^{t \cdot \boldsymbol{\psi}(\boldsymbol{s})} \qquad (\boldsymbol{\psi}(\boldsymbol{s}) = \mathsf{CGF} = \mathsf{max} \text{ eigenv. } \mathbb{W}_{\boldsymbol{s}})$$

discrete time: Giardinà, Kurchan, Peliti [PRL 96, 120603 (2006)]

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Cloning dynamics

$$\partial_{t} \hat{P}(\mathcal{C}, s) = \underbrace{\sum_{\mathcal{C}'} W_{s}(\mathcal{C}' \to \mathcal{C}) \hat{P}(\mathcal{C}', s) - r_{s}(\mathcal{C}) \hat{P}(\mathcal{C}, s)}_{\text{cloning term}} + \underbrace{\delta r_{s}(\mathcal{C}) \hat{P}(\mathcal{C}, s)}_{\text{cloning term}}$$

$$\bullet W_{s}(\mathcal{C}' \to \mathcal{C}) = e^{-s} W(\mathcal{C}' \to \mathcal{C})$$

$$\bullet r_{s}(\mathcal{C}) = \sum_{\mathcal{C}'} W_{s}(\mathcal{C} \to \mathcal{C}') \qquad r(\mathcal{C}) = \sum_{\mathcal{C}'} W(\mathcal{C} \to \mathcal{C}')$$

$$\bullet \delta r_{s}(\mathcal{C}) = r_{s}(\mathcal{C}) - r(\mathcal{C})$$

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How to take into account loss/gain of probability?

- handle a large number $N_{\rm c}$ of copies of the system
- implement a selection rule: on a time interval Δt a copy in config C is replaced by $Y = e^{\Delta t \, \delta r_s(C)}$ copies
- $\psi(s) =$ the rate of exponential growth/decay of the total population
- optionally: keep population constant by non-biased pruning/cloning

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CGF estimator:
$$\psi(s) = \langle \Psi(s) \rangle$$
 with $\Psi(s) = \log \underbrace{\prod_t \frac{N_c + Y_t - 1}{N_c}}_{\text{reconstituted population size}}$

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Biological interpretation

- \bullet copy in configuration $\mathcal{C}\equiv$ organism of $genome \ \mathcal{C}$
- dynamics of rates $W_s \equiv$ mutations
- cloning at rates $\delta r_s \equiv$ selection rendering typical the rare histories

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Generic idea

- Different dynamics can share equivalent statistical properties.
- Constrained trajectories (fixed atypical $\mathbf{k} = \mathbf{K}/t) \equiv$ pop. dynamics

An example: 4 copies, 1 degree of freedom $C = x \in \mathbb{R}$



How to perform averages? (i)

[spectral analysis]

\star Final-time distribution $\textit{p}_{end}(\mathcal{C}):$ proportion of copies in $\mathcal C$ at t

$$\begin{split} \langle N_{\rm nc}(t) \rangle_s \\ \langle N_{\rm nc}(\mathcal{C},t) \rangle_s \\ p_{\rm end}(\mathcal{C},t) &= \frac{\langle N_{\rm nc}(\mathcal{C},t) \rangle_s}{\langle N_{\rm nc}(t) \rangle_s} \end{split}$$

 $[N_{nc} = number of copies in non-constant population dynamics]$

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[spectral analysis]

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 ∂_t

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★ Final-time distribution $p_{end}(C)$: proportion of copies in C at t

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 $[N_{nc} = number of copies in non-constant population dynamics]$

Final-time distribution $p_{end}(\mathcal{C})$ governed by **right** eigenvector.

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17/06/2019 16/33

An example: 4 copies, 1 degree of freedom $C = x \in \mathbb{R}$



How to perform averages? (ii) Intermediate times

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★ Mid-time distribution $p_{ave}(C)$: proportion of copies in C at $t_1 \ll t$

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 \star Mid-time distribution $p_{ave}(\mathcal{C})$: proportion of copies in \mathcal{C} at $t_1 \ll t$

$$\begin{split} \langle N_{\rm nc}(t) \rangle_s &= \langle -|e^{t\mathbb{W}_s}|P_i\rangle N_0 \underset{t \to \infty}{\sim} e^{t\psi(s)} \langle L|P_i\rangle N_0 \\ \langle N_{\rm nc}(t|\mathcal{C},t_1) \rangle_s &= \langle -|e^{(t-t_1)\mathbb{W}_s}|\mathcal{C}\rangle \langle \mathcal{C}|e^{t_1\mathbb{W}_s}|P_i\rangle N_0 \sim e^{t\psi(s)} \langle L|\mathcal{C}\rangle \langle \mathcal{C}|R\rangle \langle L|P_i\rangle N_0 \\ p(t|\mathcal{C},t_1) &= \frac{\langle N_{\rm nc}(t|\mathcal{C},t_1)\rangle_s}{\langle N_{\rm nc}(t)\rangle_s} \underset{t \to \infty}{\sim} \langle L|\mathcal{C}\rangle \langle \mathcal{C}|R\rangle \equiv p_{\rm ave}(\mathcal{C}) \end{split}$$

How to perform averages? (ii) Intermediate times

$$\begin{array}{lll} \partial_t |\hat{P}\rangle &=& \mathbb{W}_s |\hat{P}\rangle & & \mathbb{W}_s |R\rangle = \psi(s) |R\rangle \\ e^{t\mathbb{W}_s} &\underset{t \to \infty}{\sim} e^{t\psi(s)} |R\rangle \langle L| & & \langle L|\mathbb{W}_s = \psi(s) \langle L| \\ & & \left[& \langle L| = \langle -| \ @ \ s = 0 \end{array} \right] \end{array}$$

 \star Mid-time distribution $p_{ave}(\mathcal{C})$: proportion of copies in \mathcal{C} at $t_1 \ll t$

$$\begin{split} \langle N_{\rm nc}(t) \rangle_{s} &= \langle -|e^{t\mathbb{W}_{s}}|P_{\rm i}\rangle N_{0} \underset{t \to \infty}{\sim} e^{t\psi(s)} \langle L|P_{\rm i}\rangle N_{0} \\ \langle N_{\rm nc}(t|\mathcal{C},t_{1}) \rangle_{s} &= \langle -|e^{(t-t_{1})\mathbb{W}_{s}}|\mathcal{C}\rangle \langle \mathcal{C}|e^{t_{1}\mathbb{W}_{s}}|P_{\rm i}\rangle N_{0} \sim e^{t\psi(s)} \langle L|\mathcal{C}\rangle \langle \mathcal{C}|R\rangle \langle L|P_{\rm i}\rangle N_{0} \\ p(t|\mathcal{C},t_{1}) &= \frac{\langle N_{\rm nc}(t|\mathcal{C},t_{1})\rangle_{s}}{\langle N_{\rm nc}(t)\rangle_{s}} \underset{t \to \infty}{\sim} \langle L|\mathcal{C}\rangle \langle \mathcal{C}|R\rangle \equiv p_{\rm ave}(\mathcal{C}) \end{split}$$

Mid-time distribution $p_{ave}(C)$ governed by **left** and **right** eigenvecs.

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Population dynamics & rare events

An example: 4 copies, 1 degree of freedom $C = x \in \mathbb{R}$



Example distributions for a simple Langevin dynamics



(= R(x))

ntermediate-time: $p_{ave}(x)$ (= R(x)L(x))

The small-noise crisis: systematic errors grow as $\epsilon \to 0$

CGF as a function of the noise amplitude ϵ :



Cause: as $\epsilon \to 0$, $p_{ave}(x) \& p_{end}(x) \to \text{sharply peaked at different points}$ *i.e.* the clones do not sample correctly the phase space

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Population dynamics & rare events

The feedback method

Driven/auxiliary dynamics: [Maes, Jack&Sollich, Touchette&Chetrite]

- Probability preserving
- No mismatch between pave and pend
- Constructed as

Different dynamics can share \equiv statistical properties.]

 $\mathbb{W}_{\boldsymbol{s}}^{\mathsf{aux}} = \boldsymbol{L} \mathbb{W}_{\boldsymbol{s}} \boldsymbol{L}^{-1} - \boldsymbol{\psi}(\boldsymbol{s}) \boldsymbol{1}$

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[Different dynamics can share \equiv statistical properties.]

$$\mathbb{W}_{\boldsymbol{s}}^{\mathsf{aux}} = L \mathbb{W}_{\boldsymbol{s}} L^{-1} - \psi(\boldsymbol{s}) \mathbf{1}$$

Driven/auxiliary dynamics: [Maes, Jack&Sollich, Touchette&Chetrite]

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$$\mathbb{W}_{\boldsymbol{s}}^{\mathsf{aux}} = \boldsymbol{L} \mathbb{W}_{\boldsymbol{s}} \boldsymbol{L}^{-1} - \boldsymbol{\psi}(\boldsymbol{s}) \mathbf{1}$$

- Issue: determining L is difficult
- Solution: evaluate L as L_{test} on the fly **[feedback]** and simulate

• **Iterate.** [For any *L*_{test}, the simulation is in principle correct.]

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 $\mathbb{W}_{s}^{\mathsf{test}} = L_{\mathsf{test}} \mathbb{W}_{s} L_{\mathsf{test}}^{-1}$ (induces *effective forces*)

Iterate. [For any L_{test}, the simulation is in principle correct.]

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 $\mathbb{W}_{s}^{\text{test}} = L_{\text{test}} \mathbb{W}_{s} L_{\text{test}}^{-1}$ (induces *effective forces*)

• Iterate. [For any L_{test}, the simulation is in principle correct.]

Similar in spirit to **multi-canonical** (*e.g.* Wang–Landau) approaches in static thermodynamics. [Here, one flattens the left-eigenvector of $\mathbb{W}_s^{\text{test.}}$]

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Results

Improvement of the small-noise crisis (i.i)





Physical insight: probability loss transformed into effective forces.

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Results

Improvement of the small-noise crisis (i.ii)



Much more efficient evaluation of the biased distribution. Even for a very crude (polynomial) approximation of the effective force.

Improvement of the small-noise crisis (ii)



Interacting system in 1D. Effective force: 1-, 2-, 3- body interactions only [also crude approx.].

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Finite-time and -population effects

Finite-time scaling





Estimator converges in 1/t to its infinite-time limit Understanding: the estimator is an additive observable of the pop. dyn.

Finite- N_c scaling

[fixed time]



Estimator converges in $1/N_c$ to its infinite-population limit Understanding: large N_c expansion, small-noise description

Distribution of the CGF estimator [fixed population N_c]



In the numerics: \approx Gaussian when finite- $N_{\rm c}$ scaling is ${\it O}(1/N_{\rm c})$ A way to check why one is / is not in that regime

Summary and open questions (1)

Feedback method

[with F Bouchet, R Jack, T Nemoto]

- Sampling problem (depletion of ancestors)
- On-the-fly evaluated auxiliary dynamics
- Solution to the small-noise crisis
- Systems with large number of degrees of freedom

Summary and open questions (1)

Feedback method[with F Bouchet, R Jack, T Nemoto]• Sampling problem (depletion of ancestors)• On-the-fly evaluated auxiliary dynamics• Solution to the small-noise crisis• Systems with large number of degrees of freedom

Finite-population effects

[with E Guevara, T Nemoto]

- Quantitative finite- N_{clones} scaling \rightarrow interpolation method
- Initial transient regime due to small population
- Analogy with biology: many small islands vs. few large islands?
- Question: effective forces ← selection?

Open questions (2): why is the feedback working?

Improvement of the depletion-of-ancestors problem:



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Open questions (3)

Finite-population and -time scalings

- Anomalous fluctuations (invalid 1/N_c asymptotics)
- Correct description of the meta-dynamics?
- Finite-N_c and -t scaling with feedback
- Phase transition in the distribution of the CGF estimator?

Thank you for your attention!

- * Population dynamics method with a multi-canonical feedback control Takahiro Nemoto, Freddy Bouchet, Robert L. Jack and Vivien Lecomte PRE 93 062123 (2016)
- Finite-time and finite-size scalings in the evaluation of large deviation functions: Analytical study using a birth-death process
 Takahiro Nemoto, Esteban Guevara Hidalgo and Vivien Lecomte
 PRE 95 012102 (2017)
- Finite-size scaling of a first-order dynamical phase transition: adaptive population dynamics and effective model Takahiro Nemoto, Robert L. Jack and Vivien Lecomte PRL **118** 115702 (2017)
- Finite-time and finite-size scalings in the evaluation of large deviation functions: Numerical approach in continuous time Esteban Guevara Hidalgo, Takahiro Nemoto and Vivien Lecomte PRE **95** 062134 (2017)

Supplementary material

How to perform averages?

★ Mid-time ancestor distribution:

fraction of copies (at time t_1) which were in configuration C, knowing that there are in configuration C_f at final time t_f :

$$p_{\rm anc}(\mathcal{C}, t_1; \mathcal{C}_{\rm f}, t_{\rm f}) = \frac{\langle N_{\rm nc}(\mathcal{C}_{\rm f}, t_{\rm f} | \mathcal{C}, t_1) \rangle_s}{\sum_{\mathcal{C}'} \langle N_{\rm nc}(\mathcal{C}_{\rm f}, t_{\rm f} | \mathcal{C}', t_1) \rangle_s} \underset{t_{\rm f, 1} \to \infty}{\sim} \langle L | \mathcal{C} \rangle \langle \mathcal{C} | \mathcal{R} \rangle = p_{\rm ave}(\mathcal{C})$$

The "ancestor statistics" of a configuration C_f is thus independent (far enough in the past) of the configuration C_f .









Finite-time & -size scalings matter.

Population dynamics & rare events



time \longrightarrow

[Merolle, Garrahan and Chandler, 2005]

space



Exponential divergence of the susceptibility



Probability-preserving contribution

$$\partial_t \hat{P}(\mathcal{C}, t) = \sum_{\mathcal{C}'} \left\{ \underbrace{W_s(\mathcal{C}' \to \mathcal{C}) \hat{P}(\mathcal{C}', t)}_{\text{gain term}} - \underbrace{W_s(\mathcal{C} \to \mathcal{C}') \hat{P}(\mathcal{C}, t)}_{\text{loss term}} \right\}$$

Explicit construction

Explicit construction (1/3)



Which configurations will be visited?

Configurational part of the trajectory: $\mathcal{C}_0 \to \ldots \to \mathcal{C}_{\mathcal{K}}$

$$\mathsf{Prob}\{\mathsf{hist}\} = \prod_{n=0}^{K-1} \frac{W_s(\mathcal{C}_n \to \mathcal{C}_{n+1})}{r_s(\mathcal{C}_n)}$$

where

$$r_{s}(\mathcal{C}) = \sum_{\mathcal{C}'} W_{s}(\mathcal{C} \to \mathcal{C}')$$



When shall the system jump from one configuration to the next one?

• probability density for the time interval $t_n - t_{n-1}$

$$r_{s}(\mathcal{C}_{n-1})e^{-(t_{n}-t_{n-1})r_{s}(\mathcal{C}_{n-1})}$$



When shall the system jump from one configuration to the next one?

• probability density for the time interval $t_n - t_{n-1}$

$$r_{s}(\mathcal{C}_{n-1})e^{-(t_{n}-t_{n-1})r_{s}(\mathcal{C}_{n-1})}$$

• probability not to leave C_K during the time interval $t - t_K$

 $e^{-(t-t_K)r_s(\mathcal{C}_K)}$

$$\partial_t \hat{P}(\mathcal{C}, s) = \underbrace{\sum_{\mathcal{C}'} W_s(\mathcal{C}' \to \mathcal{C}) \hat{P}(\mathcal{C}', s) - r_s(\mathcal{C}) \hat{P}(\mathcal{C}, s)}_{\text{modified dynamics}} \underbrace{+ \ \delta r_s(\mathcal{C}) \hat{P}(\mathcal{C}, s)}_{\text{cloning term}}$$

- handle a large number of copies of the system
- implement a selection rule: on a time interval Δt a copy in config C is replaced by e^{Δt δr_s(C)} copies
- $\psi(s) =$ the rate of exponential growth/decay of the total population
- optionally: keep population constant by non-biased pruning/cloning

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- handle a large number of copies of the system
- implement a selection rule: on a time interval Δt a copy in config C is replaced by $\lfloor e^{\Delta t \, \delta r_{\rm s}(C)} + \varepsilon \rfloor$ copies, $\epsilon \sim [0, 1]$
- $\psi(s) =$ the rate of exponential growth/decay of the total population
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$$\partial_t \hat{P}(\mathcal{C}, s) = \underbrace{\sum_{\mathcal{C}'} W_s(\mathcal{C}' \to \mathcal{C}) \hat{P}(\mathcal{C}', s) - r_s(\mathcal{C}) \hat{P}(\mathcal{C}, s)}_{\text{modified dynamics}} \underbrace{+ \ \delta r_s(\mathcal{C}) \hat{P}(\mathcal{C}, s)}_{\text{cloning term}}$$

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Biological interpretation

- \bullet copy in configuration $\mathcal{C}\equiv$ organism of $genome \ \mathcal{C}$
- dynamics of rates $W_s \equiv$ mutations
- cloning at rates $\delta r_s \equiv$ selection rendering atypical histories typical